1-5. (CANCELED)

6. (CURRENTLY AMENDED) A method of operating a traveling power takeoff shaft having a clutch connection with that is connected, via a clutch, to a drive motor, wherein one of a wheel_speed and a vehicle speed is known and the traveling power takeoff shaft, via a motor speed of rotation, is electronically matched in ratio with the wheel speed, whereby, the method comprising the steps of shifting a power takeoff stage, upon attainment of one of a higher and a lower threshold value of the drive motor speed of rotation, the higher threshold value corresponding to a next higher power takeoff stage and the lower threshold value corresponding to a next lower power takeoff stage, shifting will occur to one of the corresponding next higher and the next lower power takeoff stage.

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- 7. (CURRENTLY AMENDED) The method according to claim 6, further comprising the step of <u>compensating for a difference</u>, when starting must be from zero speed, a <u>difference can be compensated of between</u> a speed of rotation at said zero speed and a lower threshold speed of rotation of the motor, by <u>utilizing</u> a strong clutch-slippage of the traveling power take-off shaft.
- 8. (CURRENTLY AMENDED) The method according to claim 6, further comprising the step of <u>achieving</u>, in a case of self-driven trailers, with a knowledge of slip, by means of an evaluation by an electronic system, an optimal speed of rotation ratio between a tractor and a trailer can be achieved.
- 9. (CURRENTLY AMENDED) The method according to claim 6, further comprising the step of adjusting the ratio of <u>the</u> vehicle speed to the traveling power take-off shaft speed of rotation to <u>a</u> current demand by manual intervention during travel.
- 10. (CURRENTLY AMENDED) A method of operating a traveling power takeoff shaft connected by a clutch to a drive motor, the method comprising the steps of:

sensing one of a wheel rotational speed and a vehicle speed with a sensor;

defining a lower motor rotational speed threshold value to correspond to a next lower power takeoff stage;

C	<u>omparing the wheel rotational speed to the lower motor rotational spee</u>	<u>b£</u>
threshold value	5.1 5.	

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electronically matching rotation of a traveling power takeoff shaft to one of the wheel rotational speed and the vehicle speed, by adjusting motor rotation a rotational speed of the drive motor; [[and]]

shifting to [[a]] the next lower power takeoff stage when a next the rotational speed of the drive motor achieves the lower motor rotational speed threshold value is achieved.

- 11. (PREVIOUSLY PRESENTED) The method according to claim 10 further comprising the step of compensating for a difference in the drive motor rotation speed between a zero rotation speed and the lower motor rotation speed threshold value when, starting from the zero rotation speed, by allowing clutch slippage of the traveling power take off shaft.
- 12. (CURRENTLY AMENDED) The method according to claim 10 further comprising the step of achieving an optimal utilizing clutch slip and an electronic system to optimize a speed of rotation ratio between a tractor and a trailer by evaluation by an electronic system, with a knowledge of slip, in a case of self-driven trailers.
- 13. (PREVIOUSLY PRESENTED) The method according to claim 10, further comprising the step of adjusting a ratio of the vehicle speed to the rotation of the traveling power take-off shaft to current demand by manual intervention during travel.
- 14. (CURRENTLY AMENDED) A method of operating a traveling power takeoff shaft that is connected to a drive motor by a clutch and a takeoff shaft gear stage, the method comprising the steps of:

determining either one of a wheel rotational speed and monitoring a vehicle travel speed with a sensor; and

adapting a rotational speed of the power takeoff shaft to conform to the one of the wheel rotational speed and the vehicle travel speed by one of:

electronically shifting to a <u>next</u> higher takeoff shaft gear stage, if a rotational speed of the drive motor essentially equals an upper rotational speed threshold, and

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electronically shifting to a next lower takeoff shaft gear stage, if	E
the rotational speed of the drive motor essentially equals a lower rotational speed	
threshold;	B I
adapting engagement (slip) of the clutch of the power takeoff shaft to	F
natch a difference between the rotational speed of the power takeoff shaft at a	
ehicle travel speed of zero and the lower rotational speed threshold of the drive	
notor to a predefined ratio.	

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